**Robin Nano error typesErl.**

Err1: Hot bed exceeds the maximum temperature limit, please check the hot, whether interface sub;

Err2: nozzle exceeds the maximum temperature limit, please check whether the thermal interface sub;

Err3: hot bed more than the lowest temperature limit, please check whether the thermal interface is broken;

Err4: nozzle above the minimum temperature limits, please check whether the thermal interface is broken;

Err5: nozzle heating failure, sprinkler head did not reach setting temperature difference in a set time, is an error; Please check the assembler file Settings or to check if the power is enough;

Err6: hot bed heating failure, at the set time internal song to set temperature difference, the error; Please check the assembler file Settings or to check if the power is enough;

Err7: thermal runaway. When heating up to the target temperature, the temperature is lower than the target temperature in the set time more than the set temperature error; Please check whether the hot bourgogne E are PID, or the detection of value is appropriate.

### **Robin Nano 报错类型**

Err1:热床超过最大温度限制，请检查热敏接口是否短接；

Err2:喷头超过最大温度限制，请检查热敏接口是否短接；

Err3:热床超过最低温度限制，请检查热敏接口是否断开；

Err4:喷头超过最低温度限制，请检查热敏接口是否断开；

Err5:喷头加热失败，在设定时间内喷头没有达到设定温度差，则报错；请检查配置文件设置或检查电源功率是否足够；

Err6:热床加热失败，在设定时间内热床达到设定温度差，则报错；请检查配置文件设置或检查电源功率是否足够；

Err7:热失控；当升温到目标温度后，当前温度在设定时间内低于目标温度值超过了设定温度则报错；请检查热敏是否正常或检测PID值是否合适。